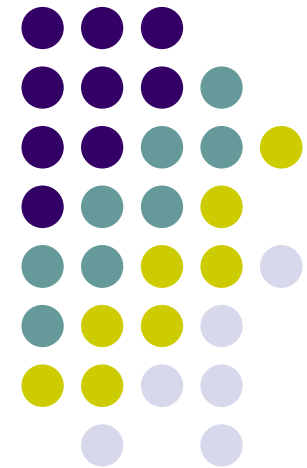


Extended Finite Element Method XFEM

Dorota Byrska
November 3, 2010





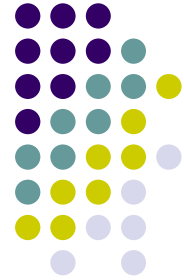
Plan of presentation

- Motivation
- General idea of XFEM
 - XFEM enrichment in 1D
 - XFEM enrichment in 2D
- Numerical Integration in XFEM
- Blending elements
- XFEM implementation
- Simple example



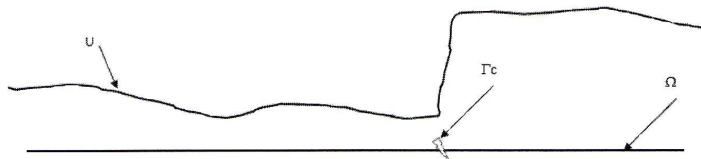
Motivation

- Difficulties in modeling discontinuous field by FEM
- Necessity of remeshing in FEM
- High computational cost of FEM
- Low accuracy of FEM in modeling cracks

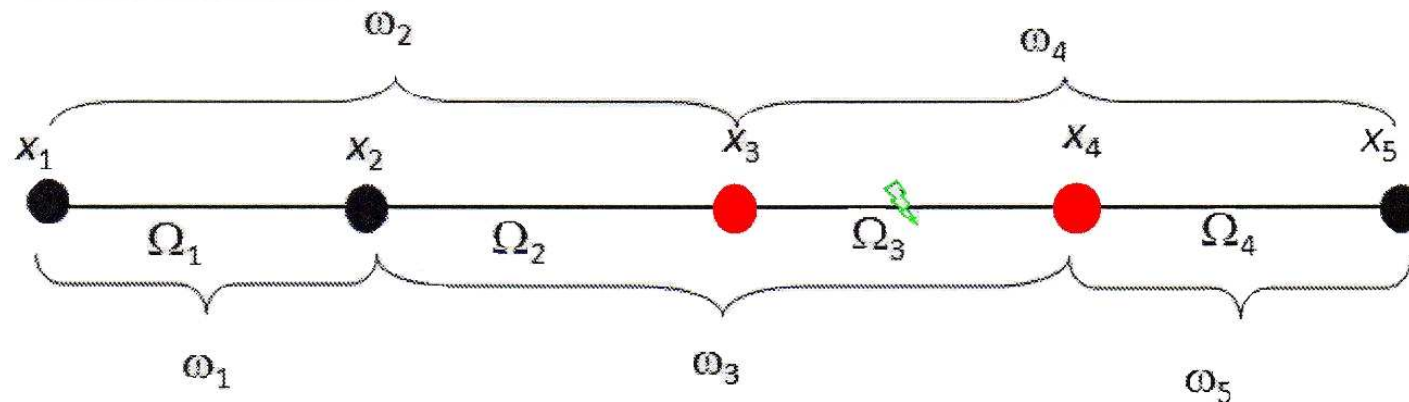


General idea of XFEM

- Discontinuous field U :



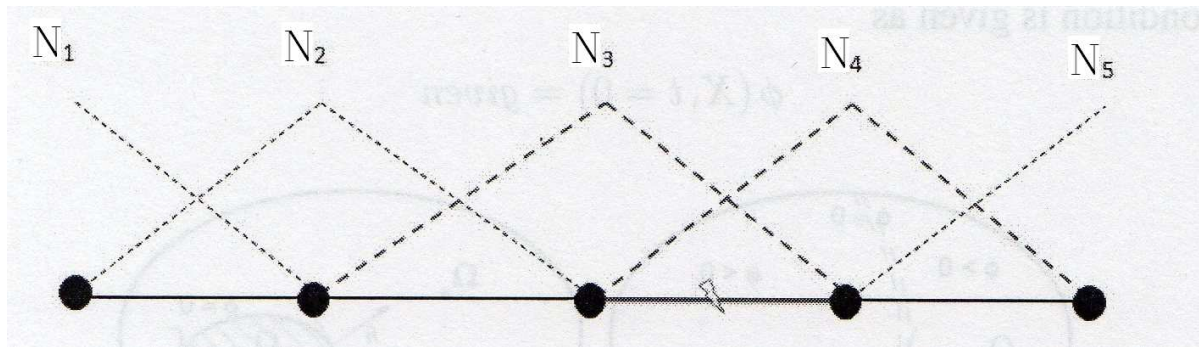
- XFEM mesh discretization and enriched nodes:





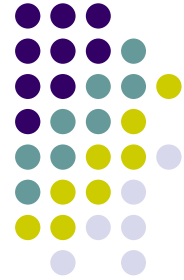
General idea of XFEM

- Standard FEM linear interpolation functions over 1D domain:



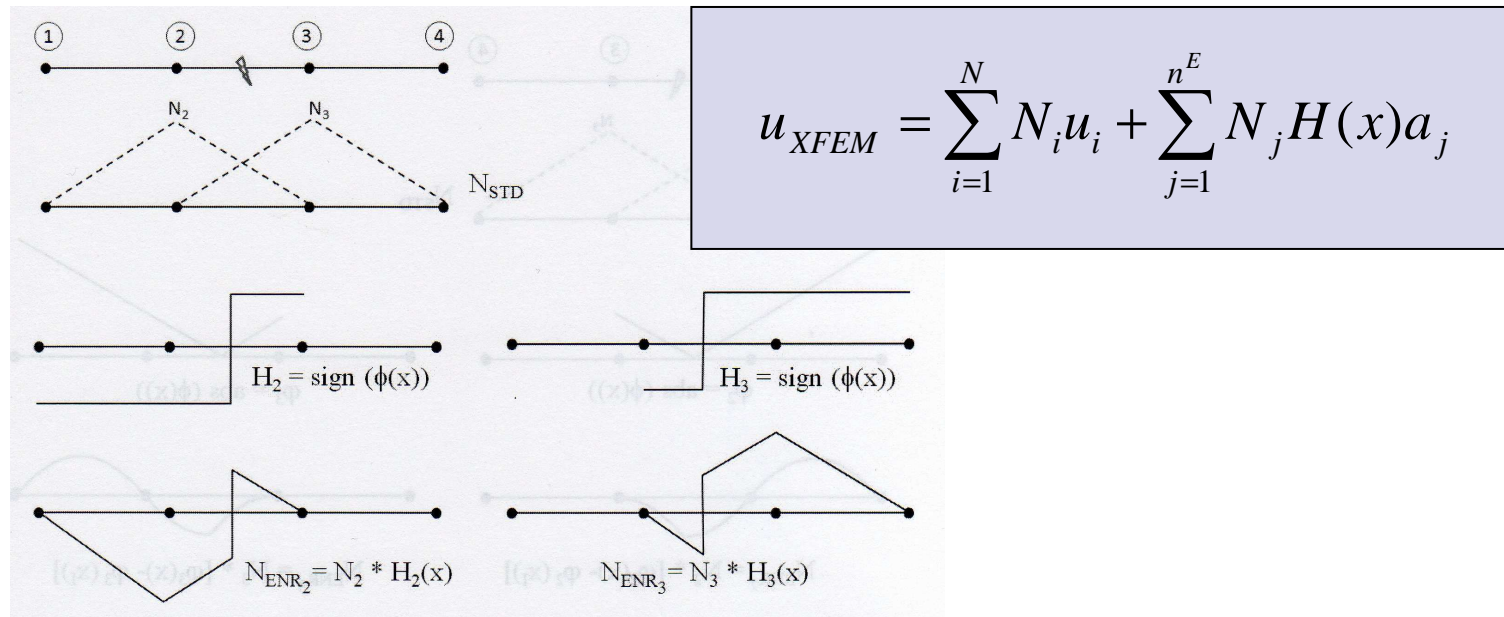
- Standard FEM approximation:

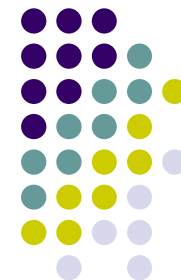
$$u^h(x) = \sum_{\forall l} N_l(x) u_l$$



General idea of XFEM

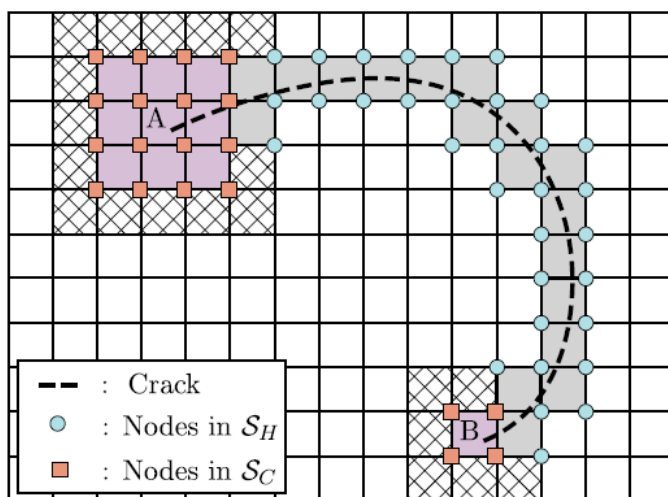
- Enriched basis function for a strong discontinuity in 1D



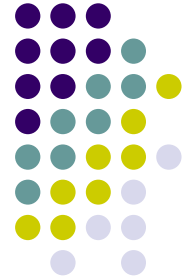


General idea of XFEM

- XFEM mesh in 2D – enriched nodes



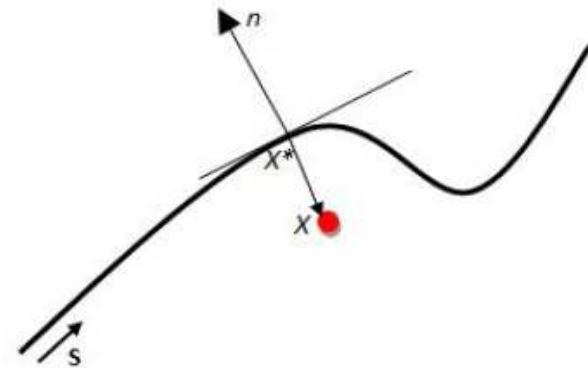
- In this case 2 types of enrichment is used:
 - Heaviside/step function in elements cut by crack
 - Asymptotic near-tip enrichment function for the elements which contain crack tip



General idea of XFEM

- XFEM approximation in 2D domain with crack tip:

$$H(x, y) = \begin{cases} 1 & \text{for } (x - x^*) \cdot n > 0 \\ -1 & \text{for } (x - x^*) \cdot n < 0 \end{cases}$$



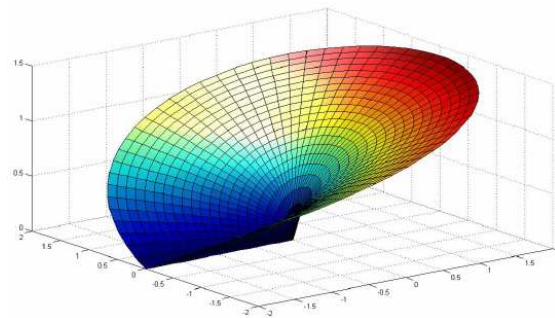
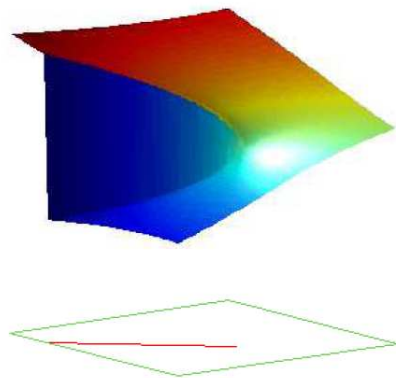
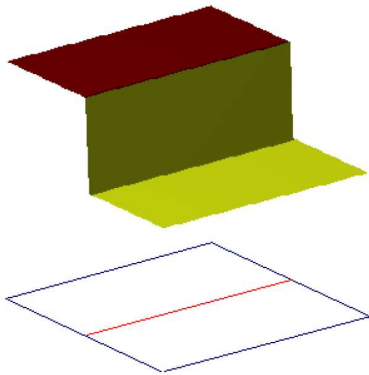
$$\{F_l(r, \theta)\}_{l=1}^4 = \left\{ \sqrt{r} \cos\left(\frac{\theta}{2}\right), \sqrt{r} \sin\left(\frac{\theta}{2}\right), \sqrt{r} \sin\left(\frac{\theta}{2}\right) \sin \theta, \sqrt{r} \cos\left(\frac{\theta}{2}\right) \sin \theta \right\}$$

$$u^h(x) = \sum_{\forall l} N_l(x) u_l + \sum_{j \in S_H} N_j(x) H(x) q_j^0 + \sum_j \sum_{k \in S_C} N_k(x) F_j(x) q_k^j$$

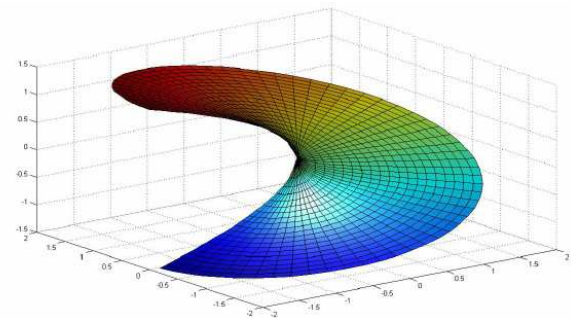


General idea of XFEM

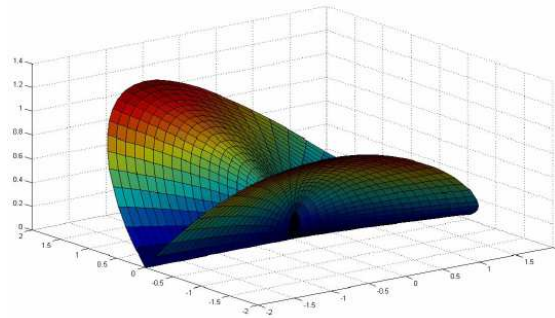
- Enriched basis for crack growth in 2D:



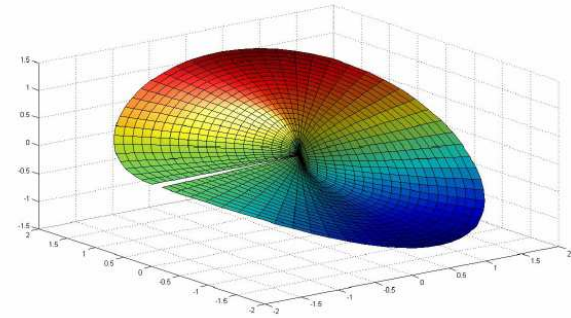
(a) $\sqrt{r} \cos\left(\frac{\theta}{2}\right)$



(b) $\sqrt{r} \sin\left(\frac{\theta}{2}\right)$



(c) $\sqrt{r} \sin\left(\frac{\theta}{2}\right) \sin\theta$

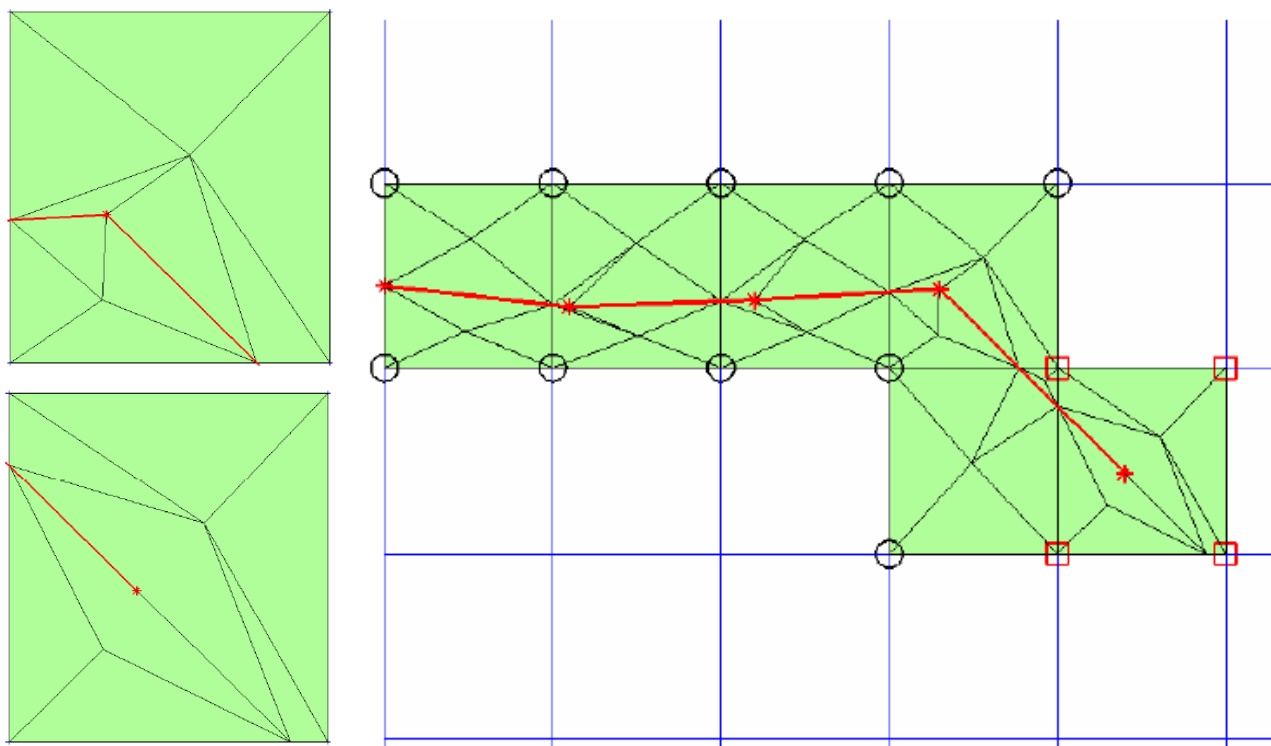


(d) $\sqrt{r} \cos\left(\frac{\theta}{2}\right) \sin\theta$

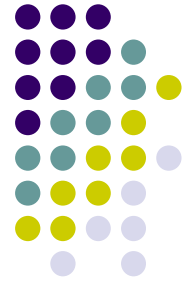


Numerical Integration in XFEM

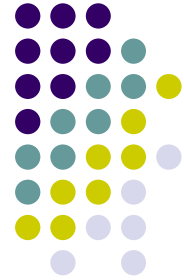
- For elements cut by the crack, modified integration scheme is practiced in XFEM



Numerical Integration in XFEM

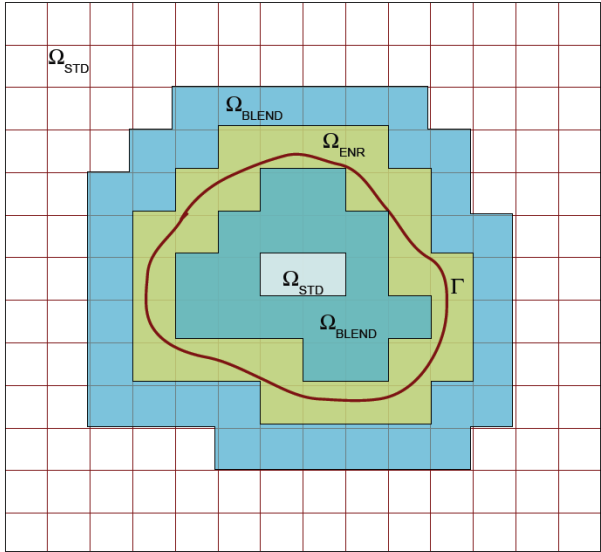


- The partitioning of an element is done only for integration purpose and no extra degrees of freedoms are added to the system unlike the usual FEM
- No conditions on the shape of sub-polygons or sub-triangles is imposed



Blending elements

- Domain Ω_{BLEND} consist elements whose some of the nodes are enriched and some of them are not. As a results of this the enrichment function is not reproduced exactly in blending elements.
- Shifted enrichment automatically removes the enrichment from the domain which is not required to be enriched:



$$u^h(x) = \underbrace{\sum_{\forall l} N_l(x)u_l}_{\text{Standard FEM}} + \underbrace{\sum_{J \in S_H} N_J(x)[H(x) - H(x_J)]q_J^0}_{\text{Step enrichment function}} + \underbrace{\sum_j \sum_{K \in S_C} N_K(x)[F^{(j)}(x) - F^{(j)}(x_K)]q_K^{(j)}}_{\text{Near-tip enrichment function}}$$



Crack initiation and growth

- Some of the commonly used crack growth criteria are:
 - Minimum strain energy density criteria
 - Maximum energy release rate criteria
 - Maximum hoop stress or maximum principal stress criteria
 - Global tracking algorithm



Crack initiation and growth

- Minimum strain energy density criteria
 - The crack initiation will occur when the minimum of the strain energy density function S reaches to some critical value S_{cr}
 - The crack will extend in a direction in which strain energy density factor possess a minimum value



Crack initiation and growth

- The minimum strain energy density factor S is given by:

$$S = a_{11}K_I^2 + 2a_{12}K_I K_{II} + a_{22}K_{II}^2 + a_{33}K_{III}^2$$

$$a_{11} = \frac{\kappa+1}{16\mu\lambda\kappa^2 \cos\theta} \left[2(1-2\nu) + \frac{\kappa-1}{\kappa} \right]$$

$$a_{12} = \frac{(\kappa^2-1)^{1/2}}{8\mu\lambda\kappa^2 \cos\theta} \left[\frac{1}{\kappa} - (1-2\nu) \right]$$

$$a_{22} = \frac{1}{16\mu\lambda\kappa^2 \cos\theta} \left[4(1-\nu)(\kappa-1) + \frac{1}{\kappa}(\kappa+1)(3-\kappa) \right]$$

$$a_{33} = \frac{1}{4\mu\lambda\kappa \cos\theta}$$

- where K_I , K_{II} , K_{III} are the mode I, II, III stress intensity factors.



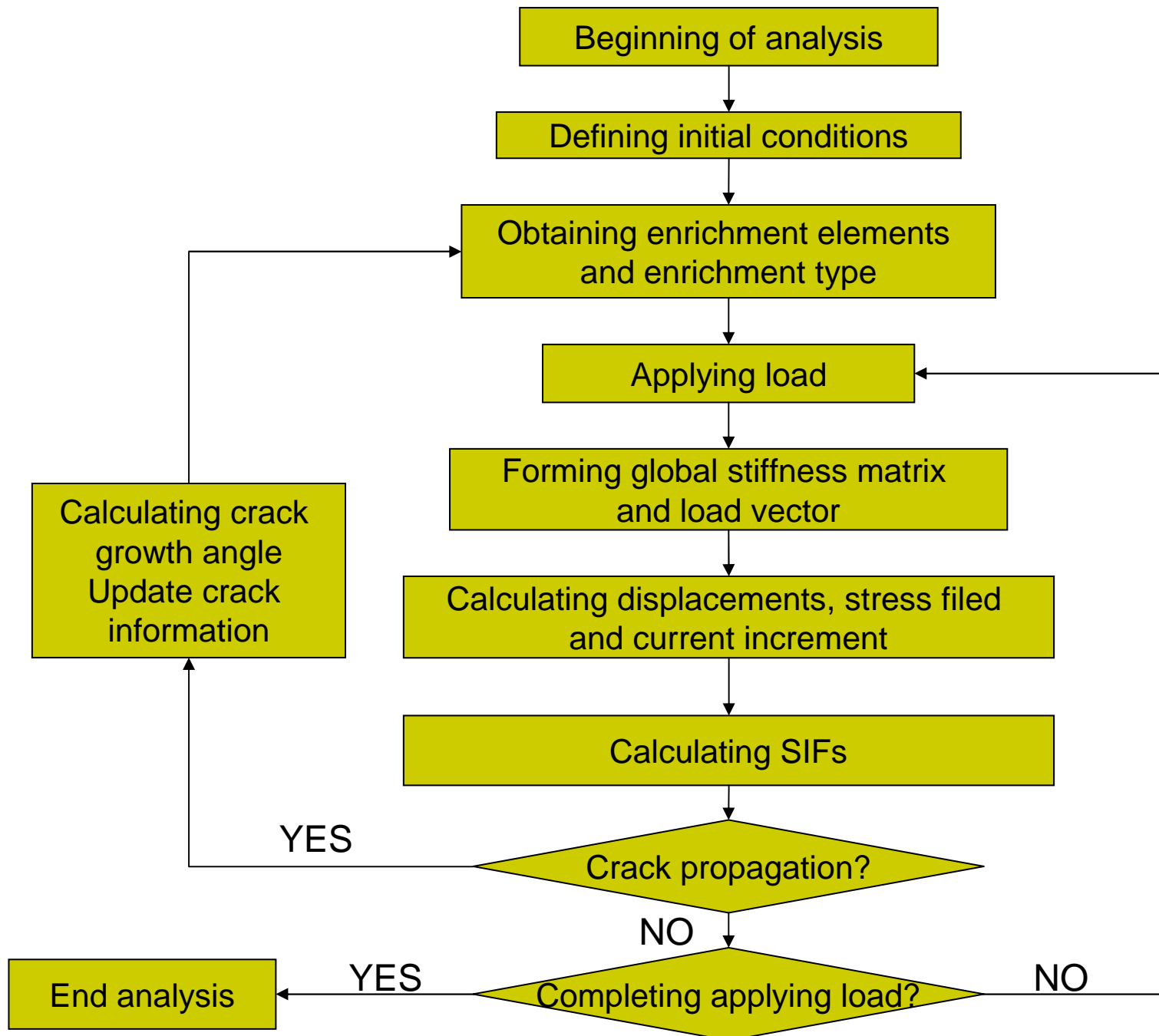
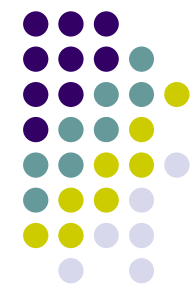
Crack initiation and growth

- The direction of propagation is determined such that:

$$\left(\frac{\partial S}{\partial \theta} \right)_{\theta=\theta_{cr}} = 0$$

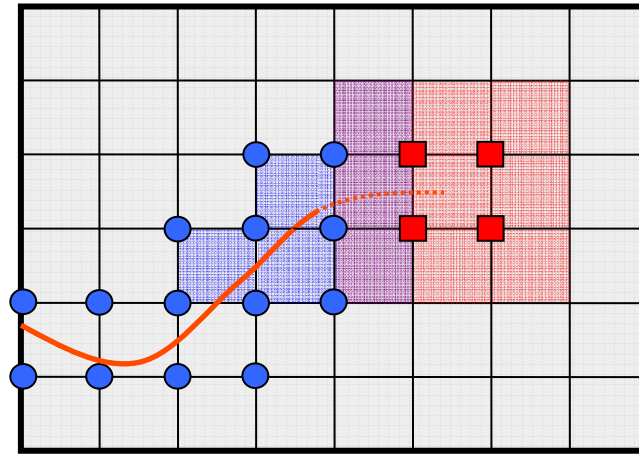
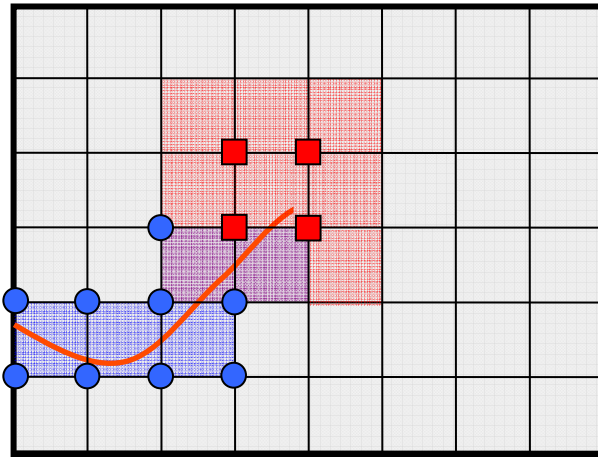
$$\left(\frac{\partial^2 S}{\partial^2 \theta} \right)_{\theta=\theta_{cr}} > 0$$

- It is worth mentioning that the criteria works well for linear elastic fracture mechanics





Updating stiffness matrix K

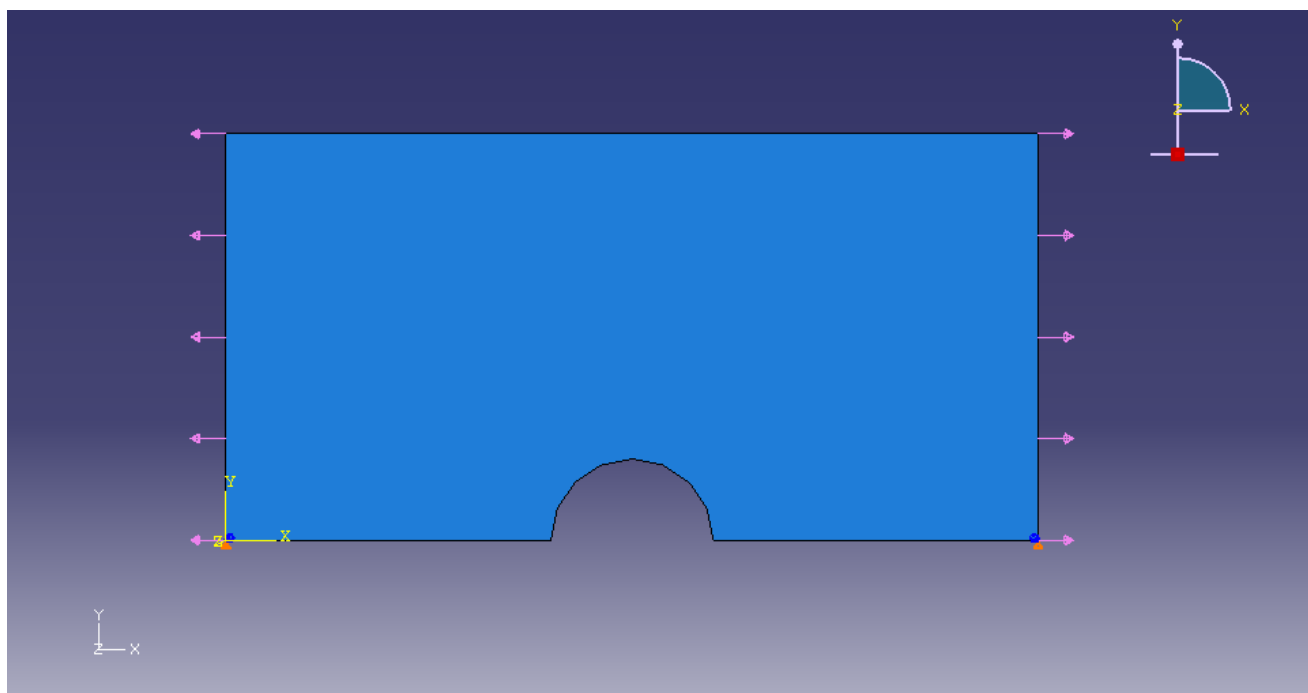


$$\begin{bmatrix} K_{uu}^1 & K_{ua}^1 & K_{ub}^1 \\ K_{ua}^{1T} & K_{aa}^1 & K_{ab}^1 \\ K_{ub}^{1T} & K_{ab}^{1T} & K_{bb}^1 \end{bmatrix} \xrightarrow{\text{Constant}} \begin{bmatrix} K_{uu}^1 & K_{ua}^1 & K_{ua}^2 & K_{ub}^2 \\ K_{ua}^{1T} & K_{aa}^1 & 0 & 0 \\ K_{ua}^{2T} & 0 & K_{aa}^2 & K_{ab}^2 \\ K_{ub}^{1T} & 0 & K_{ab}^{2T} & K_{bb}^2 \end{bmatrix}$$



Example

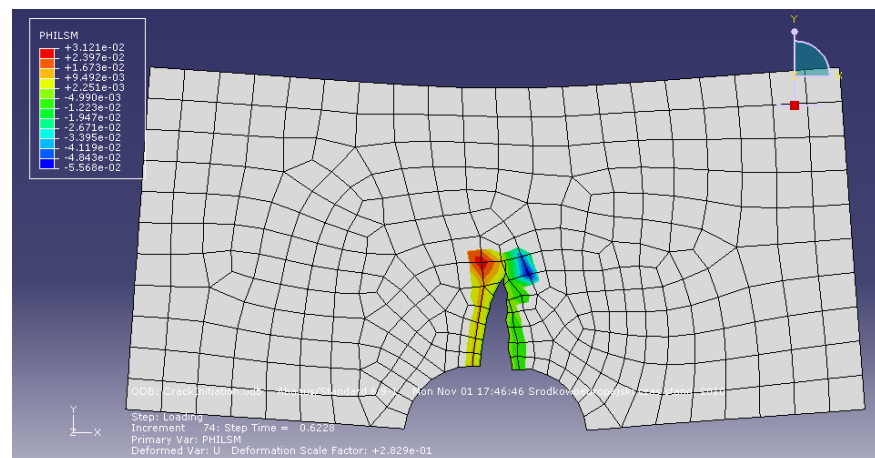
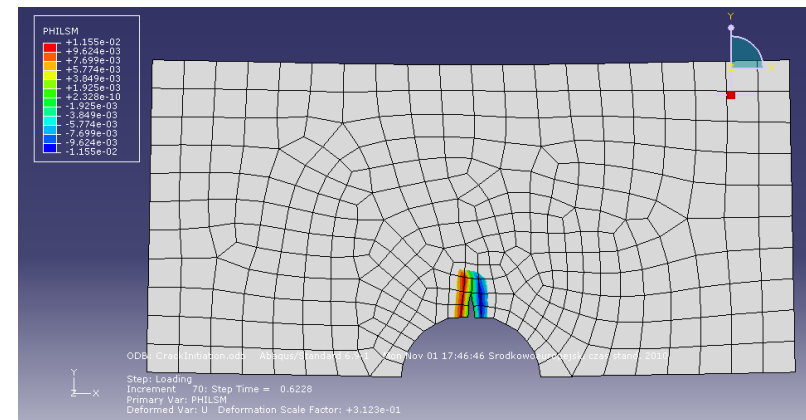
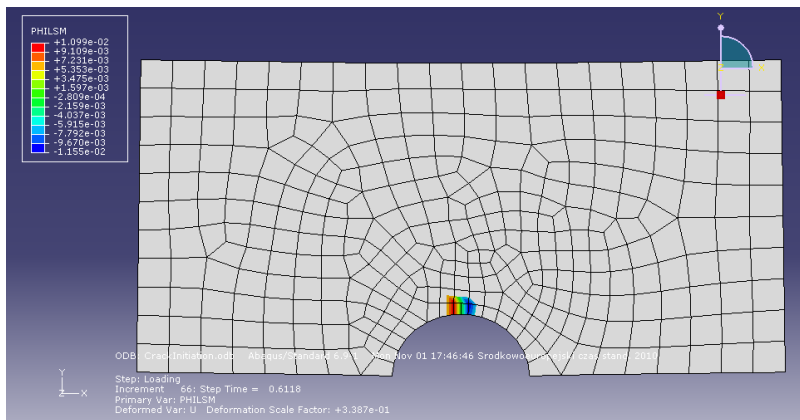
- Initiation of crack in 2D Plate – ABAQUS 6-9





Example

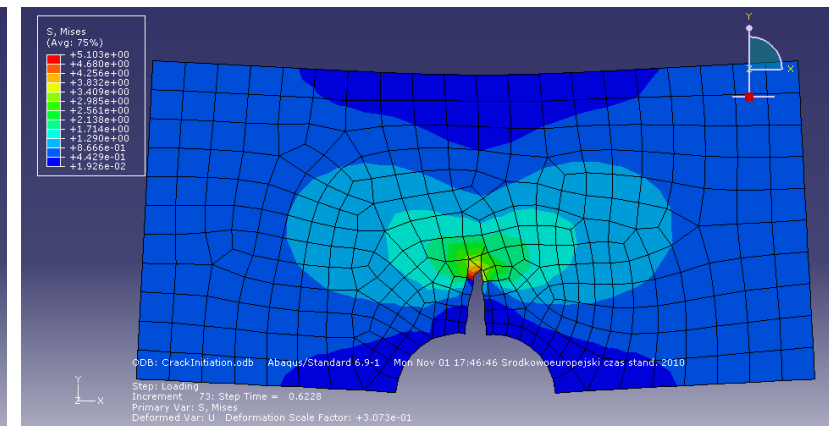
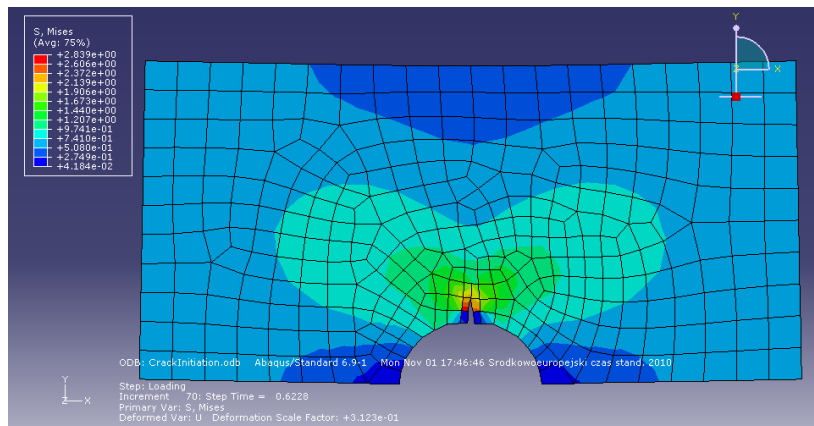
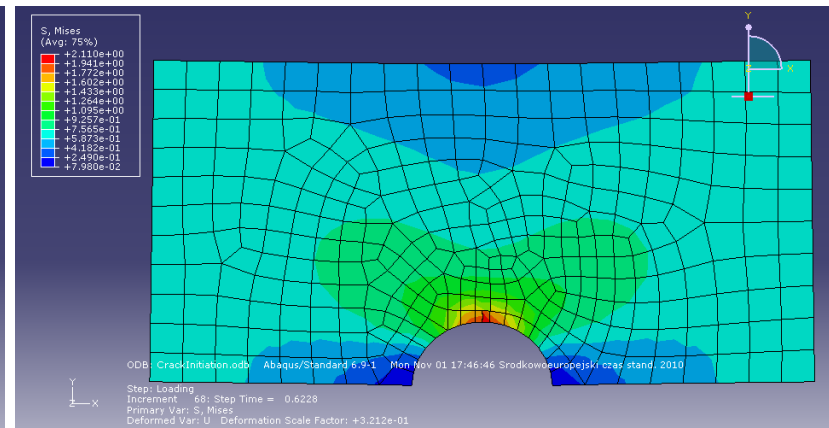
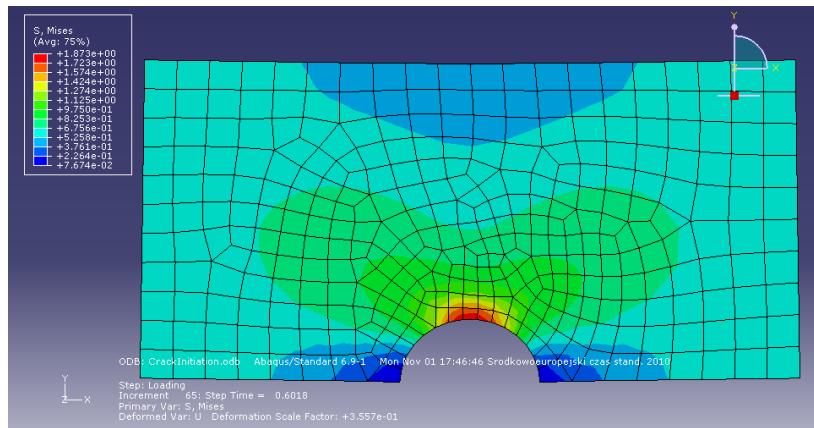
- Results: Enrichment functions values





Example

- Results: Stress relaxation





Conclusion

- Better accuracy of XFEM in comparison to FEM
- Re-meshing is not need
- Possibility of modeling discontinuities and singularities by XFEM
- Lower computationally cost



References

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Thank you for your attention